Models: P5, P5A

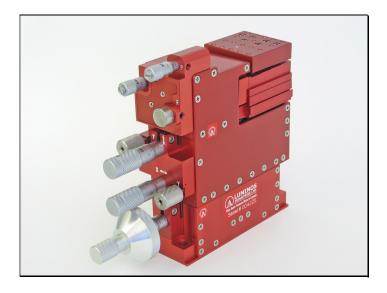
Yaw, Pitch, XYZ Manual 5-Axis Stage

SUPERIOR PERFORMANCE

Imagine a positioning system so stable and easy to adjust that singlemode optical fiber alignment is as simple as tuning a radio! No need to let go of the micrometers while adjusting - the I5000 is *extremely* touch insensitive. And with the patented ergonomic inline design, all the micrometers are easily accessible on one side - just rest your hand comfortably on the table and enjoy the ease and efficiency of quickly aligning any type of fiber. No fiber alignment challenge is too difficult - even 1-2 micron core lensed fibers can easily be aligned. This is possible because of the radical departure from conventional design.

FEATURES

- Patented Inline actuators provide ease of access.
- Patented 25x Ratio Drive[™] system affords superior resolution for far less cost.
- Small footprint allows multiple unit workstations.
- Onboard controller for actuators avoids high cost of separate motion controllers.
- Damped exterior shell design provides superior vibration and touch insensitivity.
- Lightweight aluminum construction allows system to be moved easily by other motion equipment.
- High mechanical stiffness affords rugged and stable base system.
- Patented linear dual flexure Z offers frictionless repeatable straight travel.
- Dual flexure Yaw and Pitch stages provide extreme resolution without arc error.



INNOVATION

The Luminos I5000 benefits from our patented Ratio Drive™ on the X & Y Axes. A standard micrometer, which has about 1/3 the backlash of a differential micrometer, is further improved by the 25x Ratio Drive™ resulting in a backlash of only 20 nanometers and an incredible single-sided resolution of just 1 nanometer! The roll, yaw, and pitch axes use similar leverage techniques to transform linear motion from the actuator into extremely precise rotational movements at the output.

The I5000 is extremely vibration and temperature insensitive. Internal damping eliminates many of the resonance effects typically associated with flexure stages.

ACCESSORIES

With accessories ranging from fiber array holders to contact sensors, Luminos can get you out-fitted and up-and-running quickly on your applications

AUTOMATION

With this advanced design, upgrading to automation is easy and inexpensive. Our standard, low cost stepper motor option provides the I5000 with a resolution of 4 nanometers and a 1/2 millimeter of travel on the X and Y axes. An additional 2 millimeters of manual travel is still available using the coarse adjustments. If you require more travel to be available using the actuator, consider the I5005. The Z axis provides a larger $\frac{1}{2}$ inch (12.5mm) travel on the focal axis and a resolution of 100 nanometers. Using the internal Linear Motors option, the I5000 is capable of $\frac{1}{2}$ nanometer movements on the X and Y axes. The Z axis provides a larger $\frac{1}{2}$ inch (12.5mm) travel on the focal axis and a resolution of 0.1 micrometers. The same gives a resolution of 0.2 arc seconds on the pitch and yaw axes..

ORDERING INFORMATION

Part # and Description

P5-M-M-M-M-N-1-H-N

I5000: 5-Axis Positioner, Z-Axis Actuator: Imperial Micrometer, X-Axis Actuator: Manual Micrometer, Y-Axis Actuator: Manual Micrometer, Yaw Actuator: Manual Micrometer, Pitch Actuator: Manual Micrometer, XY Linear Motors: None, XY Coarse Adjust: 40 pitch set screw, Mounting Axis: Horizontal, Side Damper: None

P5A-M-M-M-M-H-N

I5005: 5-Axis Positioner (5x), Z-Axis Actuator: Imperial Micrometer, X-Axis Actuator: Manual Micrometer, Y-Axis Actuator: Manual Micrometer, Yaw Actuator: Manual Micrometer, Pitch Actuator: Manual Micrometer, Mounting Axis: Horizontal, Side Damper: None

LUMINOS PHOTONICS

www.luminos.com 1 (613) 225-7661



<u>15000/15005 Specifications</u>

Travel						
	Axis	Actuator¹	Coarse	,	Total	
		12.7mm (0.5")	N/A		12.7mm (0.500")	
Y – vertical		0.5mm (0.02")	2mm (0.0	30")	2.5mm (0.1")	
15000	X – lateral	0.5mm (0.02")	2mm (0.0		2.5mm (0.1")	
15005	Y – vertical	2.5mm (0.1")	N/A	30)	2.5mm (0.1")	
	X – lateral	2.5mm (0.1")	N/A		2.5mm (0.1")	
Yaw		3 degrees	N/A		3 degrees	
Pitch		3 degrees			3 degrees	
Setability ² (N		3 degrees	IN/A		3 degrees	
Secability (1	Axis	P	esolution	M	ovement /Division	
	Z		0.25 micron (10μ-inch)		0.001"	
			10nm (0.4μ-inch)		1μm - 25x Ratio Drive™	
15000	, ,		n (0.4µ-inch)	1μm - 25x Ratio Drive 1μm - 25x Ratio Drive™		
	Y		` ' /	,		
15005 X Yaw		L L	50nm (2μ-inch) 50nm (2μ-inch)		5μm - 5x Ratio Drive™	
			0.2 arc sec		30 arc sec	
			0.2 arc sec		30 arc sec	
Pitch Resolution (Stepper Motor)			U.Z alt Set		Jo arc sec	
Resolution (S			ocalution	1	Total Stone	
<u> </u>	Axis		Resolution		Total Steps	
Z			100nm (4μ-inch)		128 000	
15000 Y			4nm (0.16µ-inch)		128 000 - 25x Ratio Drive™ 128 000 - 25x Ratio Drive™	
			4nm (0.16μ-inch)		128 000 - 25x Ratio Drive™ 128 000 - 5x Ratio Drive™	
15005 Y			20nm (0.8μ-inch)			
X			20nm (0.8μ-inch)		128 000 - 5x Ratio Drive™	
Yaw			0.2 arc sec		60 416	
G: 6 6	Pitch		.2 arc sec		60 416	
Stage Config	guration & Arc E			1		
Axis		FIG	Flexure Type		Arc Error	
Z			Dual		None - True Linear Motion	
	Y		Single		Max 30µm - Arc Error in Z only	
					'	
	Χ		Single		Dμm - Arc Error in Z only	
	X Yaw		Single Dual		Dμm - Arc Error in Z only None	
	X Yaw Pitch		Single		Dμm - Arc Error in Z only	
Linear Stiffn	X Yaw Pitch		Single Dual Dual		Dμm - Arc Error in Z only None None	
Linear Stiffn	X Yaw Pitch ess <i>Along Axis</i>		Single Dual Dual Stiffness	Max 30	Dμm - Arc Error in Z only None None Comments	
Linear Stiffn	X Yaw Pitch ess Along Axis Z		Single Dual Dual Stiffness 130 kN/m	Max 30	Dμm - Arc Error in Z only None None Comments red at the rotation center	
Linear Stiffn	X Yaw Pitch ess Along Axis Z Y		Single Dual Dual Stiffness L30 kN/m 95 kN/m	Max 30 measu measu	None None Comments red at the rotation center red at the rotation center	
	X Yaw Pitch ess Along Axis Z Y		Single Dual Dual Stiffness 130 kN/m	Max 30 measu measu	Dμm - Arc Error in Z only None None Comments red at the rotation center	
Linear Stiffno	X Yaw Pitch ess Along Axis Z Y X iffness	:	Single Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m	Max 30 measu measu	None None Comments red at the rotation center red at the rotation center red at the rotation center	
	X Yaw Pitch ess Along Axis Z Y X iffness About Axis		Single Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m	measu measu measu	None None None Comments red at the rotation center	
	X Yaw Pitch ess Along Axis Z Y X iffness About Axis Z - roll		Single Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m	measu measu measu measu	None None None Comments red at the rotation center	
	X Yaw Pitch ess Along Axis Z Y X iffness About Axis Z - roll Y - yaw	1	Single Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m Stiffness 75Nm/rad 00Nm/rad	measu measu measu measu measu measu measu	None None None Comments red at the rotation center	
Torsional Sti	X Yaw Pitch ess Along Axis Z Y X iffness About Axis Z - roll Y - yaw X - pitch	1	Single Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m	measu measu measu measu measu measu measu	None None None Comments red at the rotation center	
Torsional Sti	X Yaw Pitch ess Along Axis Z Y X iffness About Axis Z - roll Y - yaw X - pitch	1	Single Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m Stiffness 75Nm/rad 00Nm/rad 30Nm/rad	measu measu measu measu measu measu measu	None None None Comments red at the rotation center	
Torsional Sti	X Yaw Pitch ess Along Axis Z Y X iffness About Axis Z - roll Y - yaw X - pitch	1 1 1	Single Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m Stiffness 75Nm/rad 00Nm/rad 30Nm/rad	measu	None None None Comments red at the rotation center	
Torsional Sti	X Yaw Pitch ess Along Axis Z Y X iffness About Axis Z - roll Y - yaw X - pitch	1 1 1	Single Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m Stiffness 75Nm/rad 00Nm/rad 30Nm/rad	measu measu measu measu measu stage must	None None None Comments red at the rotation center	
Torsional Sti	X Yaw Pitch ess Along Axis Z Y X iffness About Axis Z - roll Y - yaw X - pitch bad Static Load 2.2 lbs (1kg)	1 1 1	Single Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m Stiffness 75Nm/rad 00Nm/rad 30Nm/rad	measu measu measu measu measu stage must	None None None None Comments red at the rotation center	
Torsional Sti Maximum Lo Physical Prop	X Yaw Pitch ess Along Axis Z Y X iffness About Axis Z - roll Y - yaw X - pitch bad Static Load 2.2 lbs (1kg)	1 1 1 Tra. 10	Single Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m Stiffness 75Nm/rad 00Nm/rad 30Nm/rad	measu measu measu measu measu stage must	None None None None Comments red at the rotation center	
Torsional Sti Maximum Lo Physical Prop	X Yaw Pitch ess Along Axis Z Y X Iffness About Axis Z - roll Y - yaw X - pitch oad Static Load 2.2 lbs (1kg) perties	1 1 1 Tra. 10 Spe	Single Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m Stiffness 75Nm/rad 00Nm/rad 30Nm/rad Ibs (4.5kg)	measu measu measu measu measu stage must du	None None None Comments red at the rotation center	
Torsional Sti Maximum Lo Physical Prop	X Yaw Pitch ess Along Axis Z Y X Iffness About Axis Z - roll Y - yaw X - pitch bad Static Load 2.2 lbs (1kg) perties Characteristic	1 1 1 Tra. 10 Spe	Single Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m Stiffness 75Nm/rad 00Nm/rad 30Nm/rad lbs (4.5kg)	measu measu measu measu measu stage must du	None None None Comments red at the rotation center	
Torsional Sti Maximum Lo 2 Physical Prop	X Yaw Pitch ess Along Axis Z Y X iffness About Axis Z - roll Y - yaw X - pitch bad Static Load 2.2 lbs (1kg) perties Construction	Tra. 10	Single Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m Stiffness 75Nm/rad 00Nm/rad 30Nm/rad lbs (4.5kg)	measu measu measu measu measu stage must dui	None None None Comments red at the rotation center Comments be protected from shock loading ring transport and usage Comments L & 7075 - T6 anodized	
Torsional Sti Maximum Lo 2 Physical Prop	X Yaw Pitch ess Along Axis Z Y X iffness About Axis Z - roll Y - yaw X - pitch oad Static Load 2.2 lbs (1kg) perties Construction Weight	Tra. 10	Single Dual Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m Stiffness 75Nm/rad 00Nm/rad 30Nm/rad lbs (4.5kg) ecifications Aluminum 1.5kg	measu measu measu measu stage must du	None None None None Comments red at the rotation center Comments be protected from shock loading ring transport and usage Comments L & 7075 - T6 anodized Approximate	
Maximum Lo Physical Prop Bo M	X Yaw Pitch ess Along Axis Z Y X iffness About Axis Z - roll Y - yaw X - pitch oad Static Load 2.2 lbs (1kg) perties Construction Weight ody Dimensions	5.79"	Single Dual Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m Stiffness 75Nm/rad 00Nm/rad 30Nm/rad lbs (4.5kg) ecifications Aluminum 1.5kg x 1.75" x 5.19"	measu measu measu measu measu measu stage must dui 6061	None None None None Comments red at the rotation center Comments be protected from shock loading ring transport and usage Comments L & 7075 - T6 anodized Approximate H excluding micrometers	
Maximum Lo Physical Prop Mount	X Yaw Pitch ess Along Axis Z Y X iffness About Axis Z - roll Y - yaw X - pitch bad Static Load 2.2 lbs (1kg) perties Characteristic Construction Weight bdy Dimensions ounting Height ting Configuration	5.79" 1. 0.26"	Single Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m Stiffness 75Nm/rad 00Nm/rad 30Nm/rad lbs (4.5kg) ecifications Aluminum 1.5kg x 1.75" x 5.19" 5.19"	measu measu measu measu measu measu stage must dui 6061 L x W x Base	None None None None Comments red at the rotation center red at the rotatio	
Maximum Lo Physical Prop O Boo Mount	X Yaw Pitch ess Along Axis Z Y X iffness About Axis Z - roll Y - yaw X - pitch oad Static Load 2.2 lbs (1kg) perties Construction Weight ody Dimensions ounting Height	5.79" 1. 0.26"	Single Dual Dual Dual Stiffness 130 kN/m 95 kN/m 40 kN/m Stiffness 75Nm/rad 00Nm/rad 30Nm/rad lbs (4.5kg) ecifications Aluminum 1.5kg x 1.75" x 5.19" 5.19" diameter holes	measu measu measu measu measu measu stage must dui 6061 L x W x Base 1. Abov	None None None None Comments red at the rotation center	

^{1 &#}x27;Actuator' refers to a micrometer or stepper motor.
2 Operator dependent
3 Compatible with 1.00" grid optical tables, units mount on 2" intervals with 0.25" allowance for routing of cables etc.



